

Homing sensor – PoHome1IRNPN

User's manual



Please read the following notes

- 1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice.
- 2. PoLabs does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of PoLabs products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of PoLabs or others. PoLabs claims the copyright of, and retains the rights to, all material (software, documents, etc.) contained in this release. You may copy and distribute the entire release in its original state, but must not copy individual items within the release other than for backup purposes.
- 3. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of the products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. PoLabs assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
- 4. PoLabs has used reasonable care in preparing the information included in this document, but PoLabs does not warrant that such information is error free. PoLabs assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
- 5. PoLabs devices may be used in equipment that does not impose a threat to human life in case of the malfunctioning, such as: computer interfaces, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment, and industrial robots.
- 6. Measures such as fail-safe function and redundant design should be taken to ensure reliability and safety when PoLabs devices are used for or in connection with equipment that requires higher reliability, for example: traffic control systems, anti-disaster systems, anticrime systems, safety equipment, medical equipment not specifically designed for life support, and other similar applications.
- 7. PoLabs devices shall not be used for or in connection with equipment that requires an extremely high level of reliability and safety, as for example: aircraft systems, aerospace equipment, nuclear reactor control systems, medical equipment or systems for life support (e.g. artificial life support devices or systems), and any other applications or purposes that pose a direct threat to human life.
- 8. You should use the PoLabs products described in this document within the range specified by PoLabs, especially with respect to the maximum rating, operating supply voltage range and other product characteristics. PoLabs shall have no liability for malfunctions or damages arising out of the use of PoLabs products beyond such specified ranges.
- 9. Although PoLabs endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, PoLabs products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a PoLabs product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures.
- 10. Usage: the software in this release is for use only with PoLabs products or with data collected using PoLabs products.
- 11. Fitness for purpose: no two applications are the same, so PoLabs cannot guarantee that its equipment or software is suitable for a given application. It is therefore the user's responsibility to ensure that the product is suitable for the user's application.
- 12. Viruses: this software was continuously monitored for viruses during production, however the user is responsible for virus checking the software once it is installed.
- 13. Upgrades: we provide upgrades, free of charge, from our web site at www.poscope.com. We reserve the right to charge for updates or replacements sent out on physical media.
- 14. Please contact a PoLabs support for details as to environmental matters such as the environmental compatibility of each PoLabs product. Please use PoLabs products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. PoLabs assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
- 15. Please contact a PoLabs support at support.poscope.com if you have any questions regarding the information contained in this document or PoLabs products, or if you have any other inquiries.
- 16. The licensee agrees to allow access to this software only to persons who have been informed of and agree to abide by these conditions.
- 17. Trademarks: Windows is a registered trademark of Microsoft Corporation. PoKeys, PoKeys55, PoKeys56U, PoKeys56E, PoKeys57U, PoKeys57CNC, PoScope, PoLabs and others are internationally registered trademarks.

Homing sensor – PoHome1IRNPN user's manual

Descri	ption	4				
Specifi	cations	4				
Featur	es	5				
Sensor	r wiring	5				
1.	Sensor pinout	5				
2.	NPN sensor pinout	5				
3.	Installation – connecting PoHome1IRNPN to power and PoKeys57CNC device	6				
Configuration PoHome1IRNPN						

Description

Homing sensors are based on non - mechanical working principle, which makes them highly accurate and repeatable by not having any moving parts. The Sensors have very high accuracy and a very low failure rate. PoLabs - PoHome homing sensor will ensure accuracy in tool changes, job fixtures, homing protocols, automation. The homing sensor is very easy to mount and set in the perfect position on a machine or device. The sensor has LED diodes to indicate the state of the sensor. It is a simple device and it is compatible with most CNC software and hardware.

Specifications

Specification – PoHome1IRNPN Homing sensor									
Output mode :	NPN NO. NC.								
Detection distance:	5 mm								
Detection object:	Diameter 1 mm nontransparent object								
Operating Voltage:	5-24 VDC +/-10%								
Indicator:	red LED indicator								
Response time:	0,3 ms max								
Output current:	100 mA-24VDC								
Current consumption:	<10 mA								
Residual voltage:	<1.0 V DC								
Operating temperature:	-10° - 50°C								
Short-circuit protection:	YES								
Reverse polarity protection:	YES								
Material of housing:	ABS								
IP rating:	IP64								

PoHome1IRNPN user's manual

Features

- High accuracy with no moving parts,
- Homing repeatability within 10 microns (0,01 mm),
- Water-resistant IP rating: IP64,
- Wide working voltage range 5 24 VDC,
- 2m long high-quality flex cable,
- Easy mounting using M3 screws.

Sensor wiring

- 1. Sensor pinout
- Brown (5-24 VDC),
- Blue (GND).
- Black (NO Normally Open),
- White (NC Normally Closed).
- WARNING: Connecting the power polarity in reverse will damage the sensor

2. NPN sensor pinout

NPN 3-wire standard diagram



Figure 1:Standard diagram NPN sensor

3. Installation – connecting PoHome1IRNPN to power and PoKeys57CNC device

Sensor must be wired to 5-24 V power supply that has common GND to PoKeys57CNC device. Wire the output signal of the homing sensor (black wire) to target PoKeys home/limit switch input directly.





Configuration PoHome1IRNPN

- PoKeys PlugIn settings:
- In our case we setting CNC lathe (2 axis setting motor-0, motor1)

Device configuration - PoKeys_41745 X														
[PoKeys mapp	oing Pulse engir	ne page	PoStep cor	figuration Sp	oindle E	ncoders Matrix	keyboa	rd Pendant M	iscellan	eous Sp 1	•		
	F	Pulse engine configuration									Backlash compensation			
	External 8	ch with IO 🗸 🗸	Def	ault IO	Enable safety charge pump				Enabl	Enable backlash comper				
	External o	ch with to -	Den		L Enab	Accells								
	Buffer size	Maximum (reco	mmende	d) 🗸	Charge	Chargepump pin: 0 (0 - default)					Accena pully			
		industrie (rece		u)	🗹 Drive ou	Drive output enable pins from Mach4				Durbing insul				
	Input filter	: 10 🚔 x 0.	1ms		Undate					Probing input				
			Opdate RAW position registers Force parameters undate on homing				Disabled \checkmark 🗌 I							
	Back-off at	fter homing: 100) 📮 p	ulses	Support	M62/M6	53 (disables chan	nel 8)						
		Enable out	Inv. en.	Inv. sten	Limit-	Inv	limit+	Inv.+	Home	Inv.H	On hom	ne		
	Motor 0	Ext. dedicated	4	X	Disabled	8	Ext. dedicated	4	hared with limit-	X		-		
	Motor 1	Ext. dedicated	4	X	Disabled	X	Ext. dedicated	4	hared with limit-	X		_		
	Motor 2	Ext. dedicated	4	X	Disabled	X	Disabled	X	Disabled	X		_		
	Motor 3	Ext. dedicated	4	X	Disabled	X	Disabled	×	Disabled	X		_		
	Motor 4	Ext. dedicated	4	X	Disabled	X	Disabled	X	Disabled	X				
	Motor 5	Ext. dedicated	4	X	Disabled	X	Disabled	X	Disabled	X		_		
	Motor 6	Ext. dedicated	4	X	Disabled	X	Disabled	X	Disabled	X		_		
	Motor 7	Ext. dedicated	4	X	Disabled	X	Disabled	X	Disabled	X		_		
							~ 				- -			
	<										:	>		
								ОК	Cance	1	Apply			

Figure 3:Application example (MACH 4)